B.E. (EE) Part-IV 8th Semester Examination, 2007

Process Control Instrumentation

(Elective-II) (EE-803/2)

Time: 3 hours

Full Marks: 100

Use separate answerscript for each half.

Answer SIX questions, taking THREE from each half.

Two marks are reserved for neatness in each half.

FIRST HALF

- 1. a) What is Hydrastep System? Draw and explain basic building blocks of a Hydrastep System.
 - b) Name the variables to be measured for turbine pedestal vibration control. Explain the
 principle of active sensor useful for turbine pedestal vibration velocity measurement.

[16]

- 2. a) Design a motion balance type pneumatic PI controller. How K_c and T_i can be varied in the above type controller.
 - b) Explain why signal in the range of 3-15psi is taken in any pneumatic system.
 - c) Explain the operation of a reverse action type relay.

[8+4+4]

- 3. a) What is 'swelling' and 'shrinkage' Phenomena. What is the reason behind it?
 - b) What is the difference between 3-term and 3-element controller? What are the elements to be taken in case of 3 element controller. Why this control is more efficient compared to 1E or 2E control.
 - c) What is the difference between 50% and 100% P.B. How it affects the valve movement? [6+6+4]
- 4. a) Draw and explain the use of Jet-pipe in relation with hydraulic controller.
 - b) How OFFSET can be eliminated in P+I control action? (Explain graphically).
 - c) What is Co-anda Effect? Describe the operation of a proportional controller. [4+4+8]
- 5. a) A proportional controller is used to control the level of a drum at a desired value of 500 m. Range of instrument is 0-2000 m. Proportional band is 10%. Controller has an O/P range of 0.2 to 1 kg/cm². If the output is 0.6 kg/cm², the level is at desired value, find the level corresponding to 0.2 kg/cm² and 0.52 kg/cm².
 - b) How a distributed control system (DCS) can be differentiated from a centralised control system? Draw the layered structure of a distributed control system and explain it. 18+81

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- 6. a) Explain the operation of NOTC and NOTO timing relays.
 - b) What are 'limit switches'?
 - c) A 110 V dc shunt generator is to be started with a nominal load current of 1 A. Three load resistances, 110 ohms each, are to be added in parallel after every 5 seconds such that the final armature current becomes 4 A. Draw the control circuit diagram using ladder logic to implement the above. Translate the same to a ladder logic program for any known PLC that you have used. Also give the power circuit diagram.
 - d) What is 'Instruction List' method of programming a PLC? Explain with a small example.

[3+2+8+3]

- 7. a) Describe with neat sketches, the construction and working of a rotameter. State one important advantage and one important disadvantage of the Rotameter.
 - b) A miniature pitot tube is used to measure the velocity of blood flow and the differential pressure gauge records a pressure of 1 mm. of mercury. If the density of blood is 1020 kg / m³, calculate blood velocity.
 - c) What is Reynold's number? What factors does it depend on?
 - d)Briefly state the principle of operation of a flowmeter used in case of electrically conducting fluids.

17+4+3+2

- 8. a) What is the difference between 'piezoelectric sensing' and 'piezoresistive sensing'? Explain with an example of each.
 - b) What is the basic principle of operation of a semiconductor temperature sensor? Differentiate between 'voltage output' and 'current output' types.
 - c) What is a 'Humistor'? How is it used to measure relative humidity of air?
 - d) What is a 'smart' sensor? Explain with the example of an IC-based smart sensor.

[5+4+3+4]

- 9. a) How is telemetry different from remote sensing?
 - b) In digital telemetry, what is Pulse Code Modulation (PCM)? What are its advantages?
 - c) What are the contents of the Accumulator and major flags after the following 8051 program segment is executed:

mov R0, #60

mov R1, #30

mov R2, #45

mov A, R1

add A, R2

subb A, R0

xrl A, #20

d) How is the baud rate for serial transmission determined in 8051? What are the two SFRs related to serial transmission. Write a small assembly language program to show how a byte can be serially transmitted in 8051.

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10. Write short notes on any four of the following:

 $[4 \times 4]$

- a) Orifice plates
- b) p-H meters
- c) Piezoelectric accelerometer
- d) Watch dog timer in PLC
- e) FM/FM telemetry
- f) Automation hierarchy of computer-aided process control plants
- g) Memory map of 8051

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