| | | | 376-07. | (OLD COURSE) | CD-8187 | |
|-----------|--|------------|---|---|---|----|
| o://www.h | nowtoexam.co | om | | (3 Hours) | [Total Marks: 100 | |
| | N.B. | | | remaining questions. sessary. Therefore in induction motors. in transformer. | MASTER Machine I | 10 |
| | 2. | (a) | The power input to the R0 80 kW. The rotor emf is of (i) slip (ii) rotor speed (iii) resistance per phase if rot | OTOR of a 440 V 50 Hz, 6 pole, bserved to make 100 revolution mechanical power developed (iv) for current is 65 A. er stages in 3 phase induction m | 3¢ induction motor is per minute. Calculate rotor cu loss (v) rotor | 10 |
| | 3. | (a) (b) | Explain oscillating neutral Explain excitation phenom | | | 10 |
| | 4. | | 3 zone operation. What is necessity of starter | eed characteristics of three phase in in three phase induction motor? E Derive their starting torques in te | xplain autotransformer | 10 |
| | circuit diagrams, phas (b) A 230 V, 50 Hz, 4 pole, s $r_1 = 2.3 \Omega$ $r_2 = 4.2 \Omega$ Core loss = 98 Watts Friction and windage I | | circuit diagrams, phaser di A 230 V, 50 Hz, 4 pole, single $r_1=2.3~\Omega$ $r_2=4.2~\Omega$ χ Core loss = 98 Watts Friction and windage loss If the motor is running with a | fuction motor and capacitor start capacitor run motor. Draw 10 er diagrams and torque speed charactristics. Single phase induction motor has following constants and losses: 10 $x_1 = 3.2 \Omega$ $x_2 = 3.2 \Omega$ $x_m = 74 \Omega$ $\cos s = 30$ watts with a slip of 0.05 at rated voltage and frequency, then compute wer output, torque and efficiency with its auxiliary winding open. | | |
| | | | $re_1 = 0.004 \Omega$ $xe_1 = 0$ $re_2 = 0.002 \Omega$ xe_2 No. 1 transformer is of 500 | = 0.012 Ω KVA and No. 2 is of 1000 KVA. To It they share a load of 1500 KVA | hey are connected for | 10 |
| | | (b) | | ole cage induction motors. tor at rated voltage, voltage and fre | | 10 |

resistance and rotational losses and assume const. rotor resistance.

(i) Slip at full load http://www.howtoexam.com (ii) Slip at max torque

Determine: