## Thapar Institute of Engineering and Technology Electronics and Communication Engineering Department B.E. IIIrd Year, Final Examination

Time: 3.0 Hrs. Marks:  $12 \times 6 = 72$ 

Attempt any six questions

(8)

Question 1.2: What is application of Hilbert Transformer in the field of radar and speech signal processing?

(4)

Question 2.1: Consider an IIR filter transfer function

$$H[z] = \frac{1 - 2z^{-1}}{1 + 3z^{-1}} \tag{3}$$

Obtain its Two-Band Decomposition using polyphase decomposition technique.

Question 2.2: Design a Decimator for the reduction of sampling rate of a signal from 12KHz to 400Hz (as shown in Fig. 1) for the following specifications.

Passband edge frequency  $F_p = 180Hz$ 

Passband ripple  $\delta_n = 0.002$ 

Stopband edge frequency  $F_s = 200Hz$ 

Stopband ripple  $\delta_i = 0.001$ 

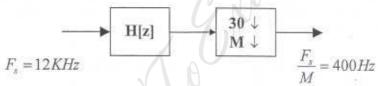


Fig. 1: Single-stage Decimator

Design Three-Stage Decimator with

 $M = M_1 \times M_2 \times M_3 = 5 \times 3 \times 2$ 

How Multistage Multirate Signal Processing helps in reducing the computational complexity?

Question 3.0: Consider a Linear Predictor of order two, described by

$$\hat{x}_n = h_1 x_{n-1} + h_2 x_{n-2}$$

where, the predictor coefficients  $h_1$  and  $h_2$  are selected to minimize the mean-square value of predictor error:

$$e_n = x_n - \hat{x}_n$$

3.1) Show that the optimum values of the predictor coefficients are given by

$$h_{o1} = \frac{\rho_1 (1 - \rho_2)}{1 - \rho_1^2} \text{ and } h_{o2} = \frac{\rho_2 - \rho_1^2}{1 - \rho_1^2}$$
with  $\rho_1 = \frac{R_X(1)}{R_Y(0)}$  and  $\rho_2 = \frac{R_X(2)}{R_Y(0)}$ 

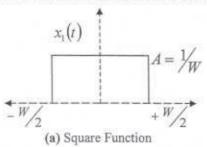
3.2) Show that the minimum mean-square error equals

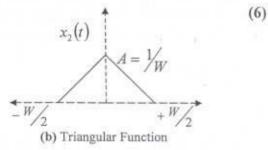
$$\xi_{\min} = \sigma_X^2 \left[ (1 - \rho_1^2) - \frac{(\rho_1^2 - \rho_2)^2}{1 - \rho_1^2} \right]$$
 (6)

where, the variance  $\sigma_\chi^2 = R_\chi(0)$ . University, placement, school and entrance exam question paper-How To Exam?

Question 4.0: Using derivative method,

4.1) Derive the Continuous-Time Fourier Transform of following





- 4.2) Derive the Discrete-Time Fourier Transform of y(n) = x(n) \* u(n). (4) where, u(n) is the Step Function in discrete-domain.
- 4.3) What is relation between correlation and convolution? (2)
- Question 5.1: Determine the signal x(n), whose z-transform is given by  $X[z] = \log(1 + az^{-1})$  |z| > |a| (3)
- Question 5.2: Using z-transform, determine the Auto-Correlation Sequence of the signal  $x(n) = a^n u(n)$ , -1 < a < +1 (4)
- Question 5.3: Describe the Goertzel Algorithm used to calculate DFT by the linear filtering approach. (5)
- Question 6.1: Prove that the FIR filter has a linear phase if its unit sample response satisfies the condition  $h(n) = \pm h(M n 1)$  for n = 0, 1, 2, ..., M 1. (4)
- Question 6.2: Describe the Chirp-z Transform Algorithm used to calculate DFT. (4)
- Question 6.3: Design a highpass filter to meet the following specifications. (4) Cutoff frequency = 250 Hz, Sampling frequency  $F_s = 1 KHz$ , and Filter length = 7.

Question 7.1: Design a lowpass filter for the following specifications.

$$H_d(\omega) = \left\{ e^{-j2\omega}, \ |\omega| \le \frac{\pi}{4} \text{ and } H_d(\omega) = \left\{ 0, \ \frac{\pi}{4} \le |\omega| \le \pi \right\} \right\}$$
 (5)

Use rectangular window  $W_n(n)=1$ ,  $0 \le n \le 4$ 

Question 7.2: Use Bilinear transformation to design a highpass digital filter using Butterworth approximation to meet the following specifications.

Stopband ripple 
$$\leq 15dB$$

Passband edge =  $150Hz$ 

Passband attenuation  $> 1dB$ 

Stopband edge =  $100Hz$ 

Sampling frequency =  $1KHz$